

# PR PROFESSIONAL-DATA-ENGINEER<sup>Q&As</sup>

Professional Data Engineer on Google Cloud Platform

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## QUESTION 1

Your team is responsible for developing and maintaining ETLs in your company. One of your Dataflow jobs is failing because of some errors in the input data, and you need to improve reliability of the pipeline (incl. being able to reprocess all failing data).

What should you do?

- A. Add a filtering step to skip these types of errors in the future, extract erroneous rows from logs.
- B. Add a try... catch block to your DoFn that transforms the data, extract erroneous rows from logs.
- C. Add a try... catch block to your DoFn that transforms the data, write erroneous rows to PubSub directly from the DoFn.
- D. Add a try... catch block to your DoFn that transforms the data, use a sideOutput to create a PCollection that can be stored to PubSub later.

Correct Answer: C

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## QUESTION 2

You're training a model to predict housing prices based on an available dataset with real estate properties. Your plan is to train a fully connected neural net, and you've discovered that the dataset contains latitude and longitude of the property. Real estate professionals have told you that the location of the property is highly influential on price, so you'd like to engineer a feature that incorporates this physical dependency.

What should you do?

- A. Provide latitude and longitude as input vectors to your neural net.
- B. Create a numeric column from a feature cross of latitude and longitude.
- C. Create a feature cross of latitude and longitude, bucketize at the minute level and use L1 regularization during optimization.
- D. Create a feature cross of latitude and longitude, bucketize it at the minute level and use L2 regularization during optimization.

Correct Answer: C

Reference <https://cloud.google.com/bigquery/docs/gis-data>

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## QUESTION 3

You work for a shipping company that has distribution centers where packages move on delivery lines to route them properly. The company wants to add cameras to the delivery lines to detect and track any visual damage to the packages in transit. You need to create a way to automate the detection of damaged packages and flag them for human review in real time while the packages are in transit. Which solution should you choose?

- A. Use BigQuery machine learning to be able to train the model at scale, so you can analyze the packages in batches.
- B. Train an AutoML model on your corpus of images, and build an API around that model to integrate with the package tracking applications.
- C. Use the Cloud Vision API to detect for damage, and raise an alert through Cloud Functions. Integrate the package tracking applications with this function.
- D. Use TensorFlow to create a model that is trained on your corpus of images. Create a Python notebook in Cloud Datalab that uses this model so you can analyze for damaged packages.

Correct Answer: B

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## QUESTION 4

Suppose you have a dataset of images that are each labeled as to whether or not they contain a human face. To create a neural network that recognizes human faces in images using this labeled dataset, what approach would likely be the most effective?

- A. Use K-means Clustering to detect faces in the pixels.
- B. Use feature engineering to add features for eyes, noses, and mouths to the input data.
- C. Use deep learning by creating a neural network with multiple hidden layers to automatically detect features of faces.
- D. Build a neural network with an input layer of pixels, a hidden layer, and an output layer with two categories.

Correct Answer: C

Traditional machine learning relies on shallow nets, composed of one input and one output layer, and at most one hidden layer in between. More than three layers (including input and output) qualifies as "deep" learning. So deep is a

defined, technical term that means more than one hidden layer.

In deep-learning networks, each layer of nodes trains on a distinct set of features based on the previous layer's output. The further you advance into the neural net, the more complex the features your nodes can recognize, since they

aggregate and recombine features from the previous layer.

A neural network with only one hidden layer would be unable to automatically recognize high-level features of faces, such as eyes, because it wouldn't be able to "build" these features using previous hidden layers that detect low-level features, such as lines.

Feature engineering is difficult to perform on raw image data.

K-means Clustering is an unsupervised learning method used to categorize unlabeled data.

Reference: <https://deeplearning4j.org/neuralnet-overview>

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## QUESTION 5

Which of the following are examples of hyperparameters? (Select 2 answers.)

- A. Number of hidden layers
- B. Number of nodes in each hidden layer
- C. Biases
- D. Weights

Correct Answer: AB

If model parameters are variables that get adjusted by training with existing data, your hyperparameters are the variables about the training process itself. For example, part of setting up a deep neural network is deciding how many "hidden" layers of nodes to use between the input layer and the output layer, as well as how many nodes each layer should use. These variables are not directly related to the training data at all. They are configuration variables. Another difference is that parameters change during a training job, while the hyperparameters are usually constant during a job.

Weights and biases are variables that get adjusted during the training process, so they are not hyperparameters.

Reference: <https://cloud.google.com/ml-engine/docs/hyperparameter-tuning-overview>

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